

# Contact Mechanics and Elements of Tribology

## Lecture 8. *Lubrication and Sealing*

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@ Centre des Matériaux (virtually)  
February 11, 2021



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A. Shvarts, V. Yastrebov

## 1 Lubrication

- Regimes of lubrication
- Derivation of the Reynolds equation
- Analytical solution for hydrostatic lubrication in bearings
- Elasto-hydrodynamic lubrication

## 2 Sealing

- Metal-to-metal face seal for nuclear power plant applications
- Fluid-structure coupling
- Results of FE numerical simulation

Acknowledgment:

Course "Scientific Computing with Applications in Tribology"

A. Almqvist, F. Pérez-Ràfols

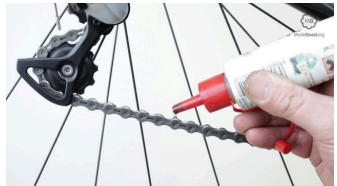
Luleå University of Technology, Sweden, 7-9 February 2017

# Lubrication: what is it?

- **Lubrication:** technique to reduce friction and wear between relatively moving surfaces by adding a solid/liquid/gas lubricant
- Studied in **Tribology** (Greek: *tribo* - "to rub", *logy* - "study of")  
'The Jost Report' (1966):  
cost of friction, wear and corrosion to UK economy P. Jost (1966)
- Applications:
  - gears
  - bearings
  - piston heads
  - human joints
  - seals
  - cams
  - metal forming
  - HDD ...
- Recent report (2017):  
23% of total world energy losses come from tribological contacts (20% friction, 3% wear)  
K. Holmberg, A. Erdemir, *Friction* (2017)



Lubricant over gears  
[www.iselinc.com](http://www.iselinc.com)



Lubricating a bike chain  
[www.madegood.org](http://www.madegood.org)

# Lubrication: what is it?

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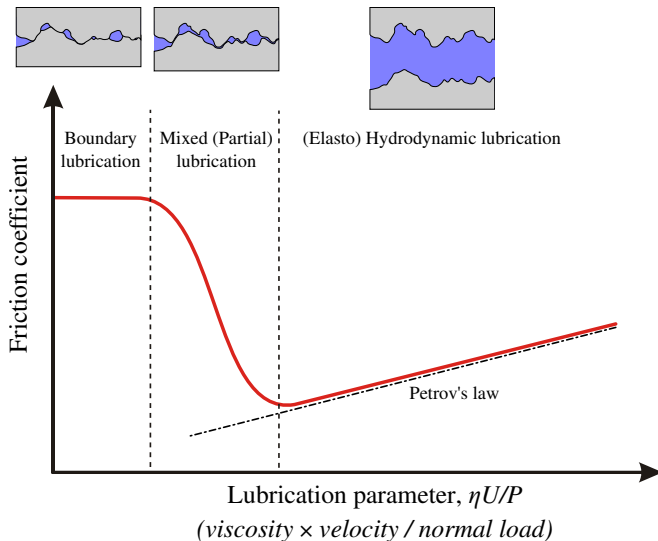


Lubricant over gears  
[www.efficientplantmag.com](http://www.efficientplantmag.com)



Lubricated roller bearing  
[www.bearingtips.com](http://www.bearingtips.com)

# Lubrication regimes: Stribeck curve



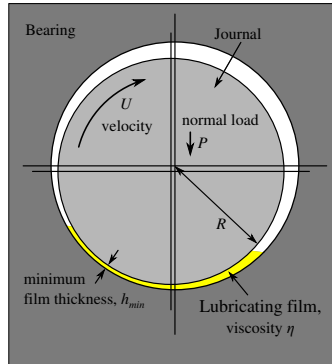
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R. Stribeck (1901)

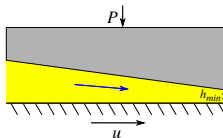
# Hydrodynamic lubrication (HL)

- Conforming surfaces
- No elastic effect
- Normal load fully supported by thin fluid film
- $h_{\min} = f(P, U, \eta, R)$
- $p \leq 5 \text{ MPa}, h_{\min} > 1 \text{ }\mu\text{m}$

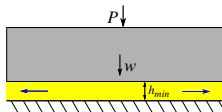
- Mechanism of pressure development in fluid film:



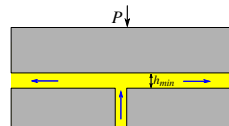
Concentric journal  
Adapted from [www.wikipedia.org](http://www.wikipedia.org)



Slider bearing



Squeeze film bearing



Externally pressurized bearing

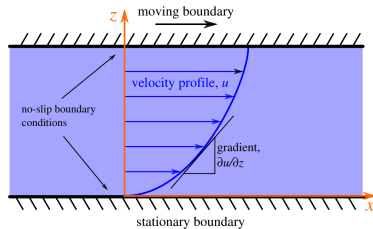
# Newtonian fluid

- Viscous stresses in flowing fluid are linearly proportional to the strain rate - the gradient of the velocity:

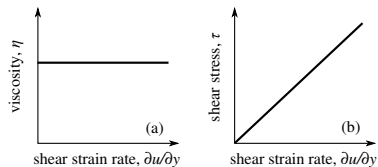
$$\tau = \eta \frac{\partial u}{\partial z}$$

- $\tau$  is the shear stress in the fluid
- $\eta$  is the viscosity (absolute, or dynamic) of the fluid
- $\frac{\partial u}{\partial y}$  is the shear strain rate
- In general 3D case for arbitrary coordinate system:

$$\tau_{ij} = \eta \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$



Laminar shear of fluid between two rigid plates



Properties of Newtonian fluid:

- (a) viscosity vs shear strain rate
- (b) shear stress vs shear strain rate

# Petrov's equation

- Shear stress:

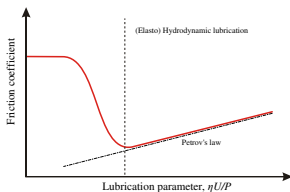
$$\tau = \eta \frac{\partial u}{\partial z} = \eta \frac{U}{h}$$

- Frictional reaction:

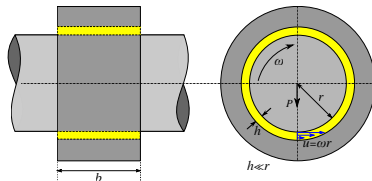
$$T = A\tau = (2\pi r b) \eta \frac{U}{h}$$

- The coefficient of friction:

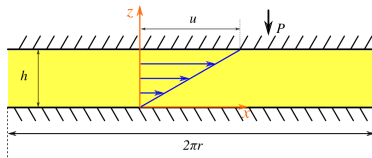
$$\mu = \frac{T}{P} = \frac{2\pi r b}{h} \frac{\eta U}{P}$$



Petrov's law  
N.P. Petrov (1883)



Concentric journal bearing



Developed journal and bearing surfaces

$r$  radius of journal

$b$  width of journal

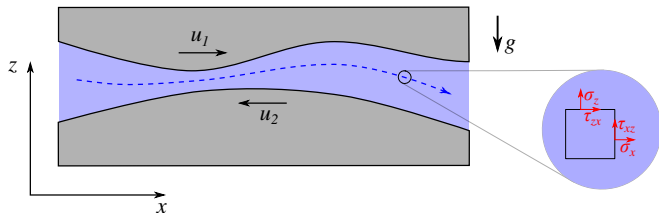
$U$  linear velocity

$P$  normal load

$h$  radial clearance



# Stresses on the surface of a fluid element



- Stresses on the surface of a fluid element:

$$\tau_{ij} = \eta \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right), \quad \tau_{ij} = \tau_{ji}$$

$$\sigma_i = -p - \frac{2}{3}\eta \nabla \cdot \underline{u} + 2\eta \frac{\partial u_i}{\partial x_i}$$

$\eta$  absolute viscosity

$p$  hydrostatic pressure

$x_i$  coordinates

$u_i$  velocity componets

$g$  acceleration of gravity

# Navier-Stokes equations

- Newton's second law of motion for a fluid element:

$$\underbrace{\rho \frac{D\mathbf{u}}{Dt}}_{\text{inertia forces}} = \underbrace{\rho \mathbf{g}}_{\text{body forces}} + \underbrace{\nabla \cdot \underline{\underline{\sigma}}}_{\text{surface forces}}$$

- Material derivative:

$$\underbrace{\frac{Du}{Dt}}_{\text{total derivative}} = \underbrace{\frac{\partial u}{\partial t}}_{\text{local derivative}} + \underbrace{u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}}_{\text{convective derivative}}$$

- Navier-Stokes equations:

$$\rho \frac{D\mathbf{u}}{Dt} = \rho \mathbf{g} - \nabla p - \frac{2}{3} \nabla (\eta \nabla \cdot \mathbf{u}) + 2 (\nabla \cdot (\eta \nabla)) \mathbf{u} + \nabla \times (\eta (\nabla \times \mathbf{u}))$$

- 4 unknowns:  $u, v, w, p$ ; 3 equations + the continuity equation

# Continuity equation

- Flux is a mass of fluid flowing per unit time through a unit area:

$$\underline{q} = \rho \underline{u}$$

- Conservation of mass: outflow of mass from a volume equals to decrease of mass within the volume (integral form):

$$\frac{dm}{dt} + \oint_S (\underline{q} \cdot \underline{n}) dS = 0$$

- The divergence theorem:

$$\oint_S (\underline{q} \cdot \underline{n}) dS = \iiint_V (\nabla \cdot \underline{q}) dV$$

- Differential form of continuity equation:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0$$

- If density  $\rho$  is constant:  $\nabla \cdot \underline{u} = 0$

# Towards the Reynolds equation

- Introducing dimensionless variables:

$$X = \frac{x}{l_0}, \quad Y = \frac{y}{b_0}, \quad Z = \frac{z}{h_0}, \quad T = \frac{t}{t_0}, \quad \bar{u} = \frac{u}{u_0}$$

$$\bar{v} = \frac{v}{v_0}, \quad \bar{w} = \frac{w}{w_0}, \quad \bar{\rho} = \frac{\rho}{\rho_0}, \quad \bar{\eta} = \frac{\eta}{\eta_0}, \quad P = \frac{h_0^2 p}{\eta_0 u_0 l_0}$$

- Reynolds number:

$$\mathcal{R} = \frac{\text{Inertia}}{\text{Viscous}} = \frac{\rho_0 u_0 l_0}{\eta_0}$$

- Thin fluid film:  $h_0 \ll l_0, \quad \mathcal{R} \ll 1$

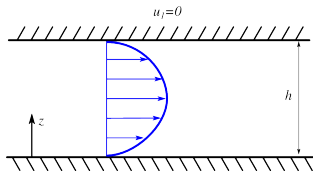
$$\frac{\partial p}{\partial x} = \frac{\partial}{\partial z} \left( \eta \frac{\partial u}{\partial z} \right)$$

$$\frac{\partial p}{\partial y} = \frac{\partial}{\partial z} \left( \eta \frac{\partial v}{\partial z} \right)$$

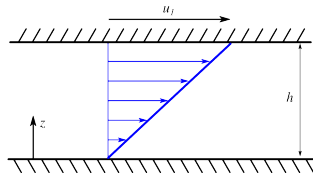
$$\frac{\partial p}{\partial z} = 0 \rightarrow p = p(x, y)$$

# Velocity profile

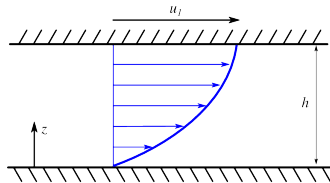
$$u = \underbrace{\frac{\partial p}{\partial x} \frac{z^2 - zh}{2\eta}}_{\text{Poiseuille flow}} + \underbrace{u_1 \frac{z}{h} + u_2 \left(1 - \frac{z}{h}\right)}_{\text{Couette flow}}$$



At rest,  $u_2=0$   
Poiseuille flow



At rest,  $u_2=0$   
Couette flow



At rest,  $u_2=0$

# Calculating flow rates

$$u = \frac{\partial p}{\partial x} \frac{z^2 - zh}{2\eta} + u_1 \frac{z}{h} + u_2 \left(1 - \frac{z}{h}\right)$$

$$v = \frac{\partial p}{\partial y} \frac{z^2 - zh}{2\eta} + v_1 \frac{z}{h} + v_2 \left(1 - \frac{z}{h}\right)$$

Flow rate per unit width in x and y directions:

$$q'_x = \int_0^h u dz = -\frac{h^3}{12\eta} \frac{\partial p}{\partial x} + \frac{u_1 + u_2}{2} h$$

$$q'_y = \int_0^h v dz = -\frac{h^3}{12\eta} \frac{\partial p}{\partial y} + \frac{v_1 + v_2}{2} h$$

Integrating continuity equation across film thickness:

$$\int_0^h \left[ \frac{\partial \rho}{\partial t} + \nabla \cdot \underline{u} \right] dz = 0$$

# Reynolds equation

- General form in 3D:

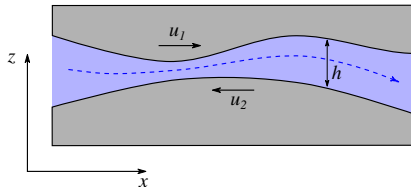
$$\frac{\partial}{\partial x} \left( \frac{\rho h^3}{12\eta} \frac{\partial p}{\partial x} \right) + \frac{\partial}{\partial y} \left( \frac{\rho h^3}{12\eta} \frac{\partial p}{\partial y} \right) = \frac{(u_1 + u_2)}{2} \frac{\partial(\rho h)}{\partial x} + \frac{(v_1 + v_2)}{2} \frac{\partial(\rho h)}{\partial y} + h \frac{\partial \rho}{\partial t}$$

- If  $\rho, \eta$  are constant:

$$\frac{1}{12\eta} \frac{\partial}{\partial x} \left( h^3 \frac{\partial p}{\partial x} \right) + \frac{1}{12\eta} \frac{\partial}{\partial y} \left( h^3 \frac{\partial p}{\partial y} \right) = \frac{(u_1 + u_2)}{2} \frac{\partial h}{\partial x} + \frac{(v_1 + v_2)}{2} \frac{\partial h}{\partial y}$$

- In 2D:

$$\frac{\partial}{\partial x} \left( h^3 \frac{\partial p}{\partial x} \right) = 6\eta(u_1 + u_2) \frac{\partial h}{\partial x}$$



# Physically relevant models

- Non-Newtonian fluid:

$$\eta = f\left(\frac{du}{dz}\right)$$

- Viscosity-pressure dependency: Barus law

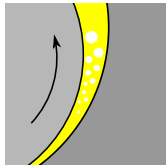
$$\eta(p) = \eta_0 e^{\alpha p}$$

- Fluid compressibility:

$$K = -V \frac{dp}{dV} = \rho \frac{dp}{d\rho}$$

$$\rho = \rho_0 e^{(p-p_0)/K}$$

- Cavitation: process of bubble generation due to local pressure decline below saturated vapor pressure





# Step slider bearing

- Reynolds equation  
( $\rho = \text{const}, \eta = \text{const}$ ):

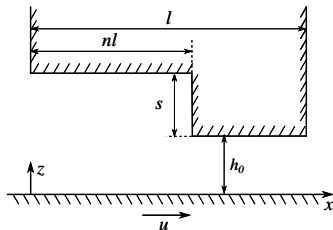
$$\frac{d}{dx} \left( h^3 \frac{dp}{dx} \right) = 6u\eta \frac{dh}{dx}$$

- Constant film thickness in both sections:

$$h(x) = \begin{cases} h_0 + s & 0 < x < nl \\ h_0 & nl < x < l \end{cases}$$

$$\frac{d^2 p}{dx^2} = 0, \quad x \in (0; nl) \cup (nl; l)$$

$$\frac{dp}{dx} = \text{const}, \quad x \in (0; nl) \cup (nl; l)$$



# Step slider bearing

- Continuity of pressure:

$$p|_{x=nl-0} = p|_{x=nl+0} = p_m$$

$$nl \left( \frac{dp}{dx} \right)_i = -(1-n)l \left( \frac{dp}{dx} \right)_o$$

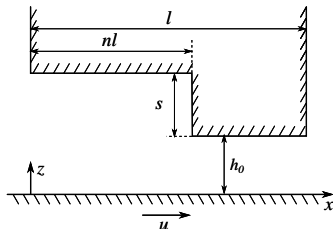
- Continuity of flow rate:

$$q'_{x,i} = q'_{x,o}$$

$$-\frac{(h_0 + s)^3}{12\eta} \left( \frac{dp}{dx} \right)_i + \frac{u(h_0 + s)}{2} = -\frac{h_0^3}{12\eta} \left( \frac{dp}{dx} \right)_o + \frac{uh_0}{2}$$

- Maximum pressure:

$$p_m = 6\eta ul \left[ \frac{n(1-n)s}{(1-n)(h_0 + s)^3 + nh^3} \right]$$



# Step slider bearing

- Pressure distribution:

$$p(x) = \begin{cases} p_m \frac{x}{nl} & 0 < x < nl \\ p_m \frac{l-x}{(1-n)l} & nl < x < l \end{cases}$$

$$p_m = 6\eta ul \left[ \frac{n(1-n)s}{(1-n)(h_0 + s)^3 + nh^3} \right]$$

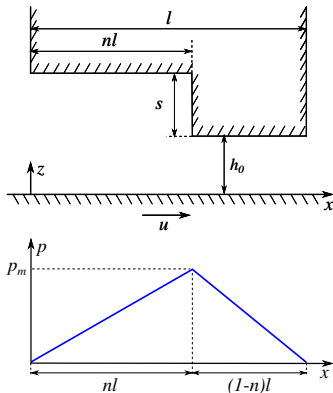
- Optimal bearing configuration to produce the largest  $p_m$ :

$$\frac{\partial p_m}{\partial n} = 0 \quad \text{and} \quad \frac{\partial p_m}{\partial s} = 0$$

$$\begin{cases} (1-n)^2(h_0 + s)^3 - n^2h_0^3 = 0 \\ (1-n)(h_0 + s)^2(h_0 - 2s) + nh_0^3 = 0 \end{cases}$$

- Optimal values:

$$\frac{h_0}{s} = 1.155, \quad n = 0.7182$$



# Inclined slider bearing

- Reynolds equation  
( $\rho = \text{const}, \eta = \text{const}$ ):

$$\frac{d}{dx} \left( h^3 \frac{dp}{dx} \right) = 6u\eta \frac{dh}{dx}$$

- Integrating:

$$h^3 \frac{dp}{dx} = 6u\eta h + C$$

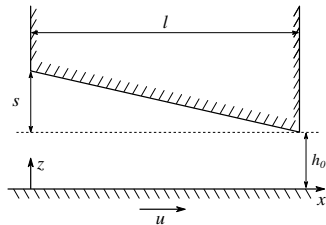
$$\frac{dp}{dx} = 0 \rightarrow h = h_m \Rightarrow C = 6u\eta h_m$$

$$\frac{dp}{dx} = 6\eta u \left( \frac{h - h_m}{h^3} \right)$$

$$h(x) = h_0 + s \left( 1 - \frac{x}{l} \right)$$

- Introducing dimensionless variables:

$$X = \frac{x}{l}, \quad H = \frac{h}{s}, \quad H_m = \frac{h_m}{s}, \quad H_0 = \frac{h_0}{s} \Rightarrow P = \frac{ps^2}{\eta ul}$$



# Inclined slider bearing

- Dimensionless Reynolds equation:

$$\frac{dP}{dX} = 6 \left( \frac{H - H_m}{H^3} \right)$$

$$H = H_0 + 1 - X, \quad \frac{dH}{dX} = -1$$

- Integrating:

$$P = 6 \int \left( \frac{1}{H^2} - \frac{H_m}{H^3} \right) dX = 6 \left( \frac{1}{H} - \frac{H_m}{2H^2} \right) + C$$

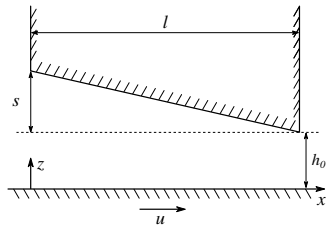
- BCs:

$$P = 0 \text{ when } X = 0 \rightarrow H = H_0 + 1$$

$$P = 0 \text{ when } X = 1 \rightarrow H = H_0$$

$$H_m = \frac{2H_0(1 + H_0)}{1 + 2H_0}, \quad C = -\frac{6}{1 + 2H_0}$$

$$P(X) = \frac{6X(1 - X)}{(H_0 + 1 - X)^2(1 + 2H_0)}$$



# Inclined slider bearing

- Dimensionless pressure distribution:

$$P(X) = \frac{6X(1-X)}{(H_0 + 1 - X)^2(1 + 2H_0)}$$

- Dimensionless coordinate of maximum:

$$X_m = \frac{1 + H_0}{1 + 2H_0}$$

- Dimensionless maximal pressure:

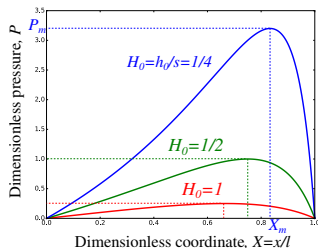
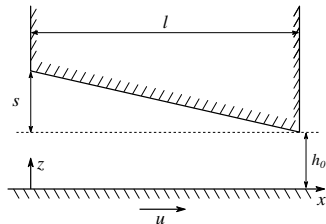
$$P_m = \frac{3}{2H_0(1 + H_0)(1 + 2H_0)}$$

- Dimensional maximal pressure:

$$p = P \frac{\eta u l}{s^2}, \quad p_m = \frac{3\eta u l s}{2h_0(s + h_0)(s + 2h_0)}$$

- Optimal shoulder height:

$$\partial p_m / \partial s = 0 \rightarrow s_{\text{opt}} = \sqrt{2}h_0$$



# Elastohydrodynamic lubrication (EHL)

- Non-conforming surfaces
- Elastic deflection of solid walls
- Viscosity-pressure dependence:  
 $\eta(p) = \eta_0 \exp \xi p$
- Hard EHL (metal parts):

$$0.5 \text{ GPa} \leq p \leq 3 \text{ GPa}$$

$$0.1 \text{ } \mu\text{m} \leq h_{\min} \leq 1 \text{ } \mu\text{m}$$

- gears
- rolling bearings
- cams

- Soft EHL (polymer):

$$p \approx 1 \text{ MPa}$$

$$h_{\min} \approx 1 \text{ } \mu\text{m}$$

- seals
- human joints
- tires



Needle roller bearing  
[www.farazbearing.com](http://www.farazbearing.com)

Bevel gear [www.linngear.com](http://www.linngear.com)

# Elastohydrodynamic lubrication (EHL)

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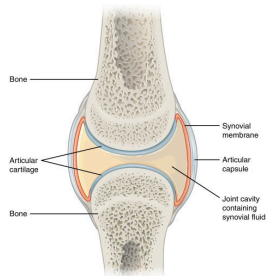
- gears
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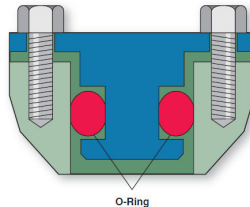
$$p \approx 1 \text{ MPa}$$

$$h_{\min} \approx 1 \text{ } \mu\text{m}$$

- seals
- human joints
- tires



Nontrivial joint  
[www.wikipedia.org](http://www.wikipedia.org)



O-ring seal  
[www.ecosealthailand.com](http://www.ecosealthailand.com)



# Elastohydrodynamic lubrication (EHL)

- Reynolds equation:

$$\frac{d}{dx} \left( \frac{h^3}{\eta} \frac{dp}{dx} \right) = 12u \frac{dh}{dx}$$

- Viscosity-pressure dependence (Barus law):

$$\eta(p) = \eta_0 e^{\xi p}$$

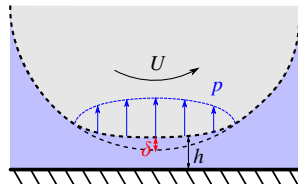
- Film shape:

$$h(x) = h_0 + S(x) + \delta(x)$$

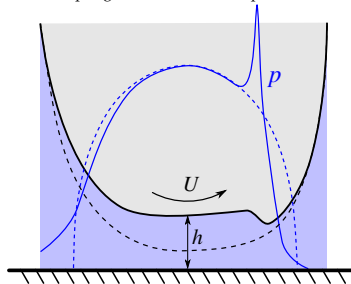
$$\begin{array}{ll} h_0 & \text{constant} \\ S(x) = \frac{x^2}{2R} & \text{undeformed geometry} \\ \delta(x) & \text{elastic deformation} \end{array}$$

- Contact constraints:

$$\begin{cases} h_0 + S(x) + \delta(x) = 0, & p > 0 \\ h_0 + S(x) + \delta(x) > 0, & p = 0 \end{cases}$$



Coupling of fluid and elastic problems



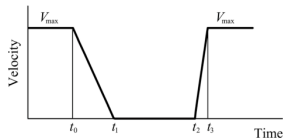
Results of numerical simulations<sup>[1,2]</sup>

[1] D. Dowson, *Wear* (1995)

[2] B.J. Hamrock, "Fundamental of fluid film lubrication" (1991)

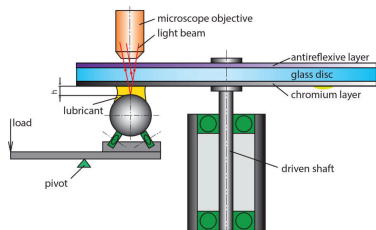
# EHL film thickness: experimental observation

- Ball-on-disk optical tribometer
- Measurement based on light interference principle
- Unidirectional start-stop-start motion
- Important for study of rolling contact fatigue and wear



Unidirectional start-stop-start motion<sup>[1]</sup>

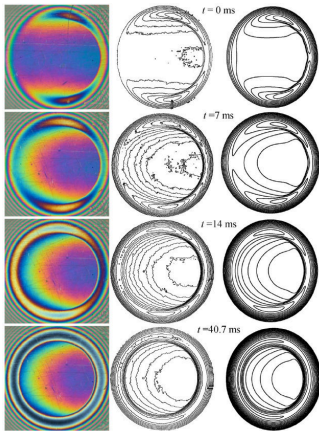
[1] P. Sperka et al, *Journal of Tribology* (2014)



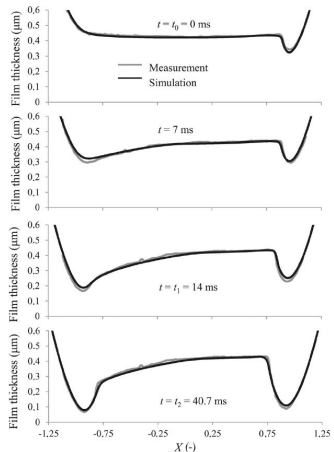
Ball-on-disk apparatus with interferometry<sup>[2]</sup>

[2] D. Kostal et al, *Journal of Tribology* (2017)

# EHL film thickness: experimental observation



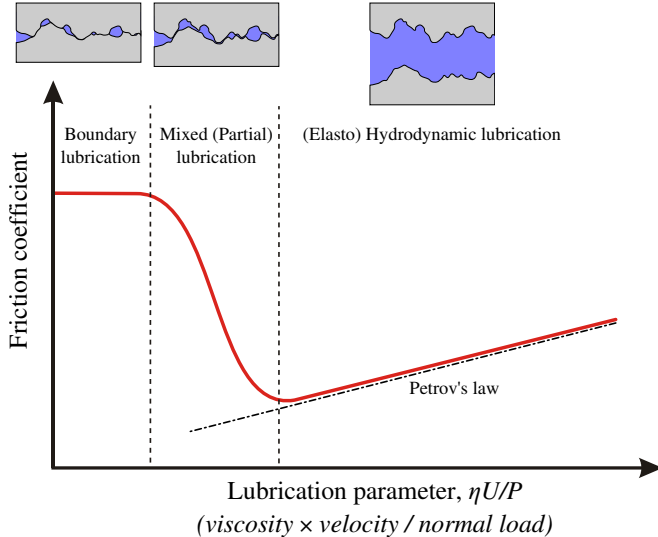
Left to right:  
snapshots of interferograms, film thickness contour  
maps, results of numerical simulation<sup>[1]</sup>



Midplane film thickness profiles along rolling  
direction<sup>[1]</sup>

[1] P. Sperka et al, *Journal of Tribology* (2014)

# Lubrication regimes: Stribeck curve



Adapted from [www.wikipedia.org](http://www.wikipedia.org)

# Boundary lubrication

- Asperities come in contact
- $1 \text{ nm} \leq h_{\min} \leq 10 \text{ nm}$
- Bulk lubricant properties (i.e. viscosity) are not important
- Physical and chemical properties of the surface and of the fluid film are important
- Lubricant film of molecular size<sup>[1]</sup>
- Breakdown of lubricant film at localized regions<sup>[2]</sup>, frictional force:

$$F = A (\alpha s_m + (1 - \alpha) s_l)$$

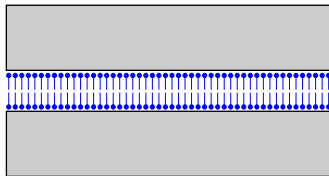
$A$  the area that supports the load

$\alpha$  fraction of breakdown area

$s_m$  shear stress in solid contact

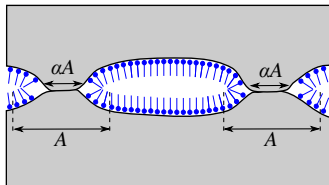
$s_l$  shear stress in the lubricating film

Therefore, if  $\alpha$  - const, then  $F \propto A$ .



The frictional resistance is due to interaction between the outer surfaces of the adsorbed monolayers without any solid contact occurring<sup>[1]</sup>

[1] W.B. Hardy, (1936)



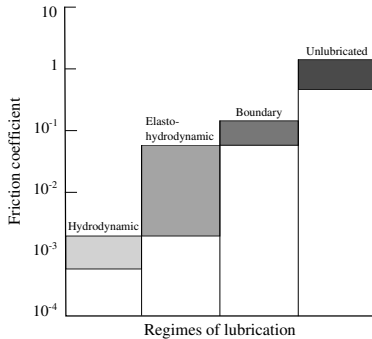
Mechanism involving breakdown of the lubricant film at small localized regions<sup>[2]</sup>

[2] F.P. Bowden and D. Tabor, "The friction and Lubrication of Solids (1950)

# Mixed (partial) lubrication

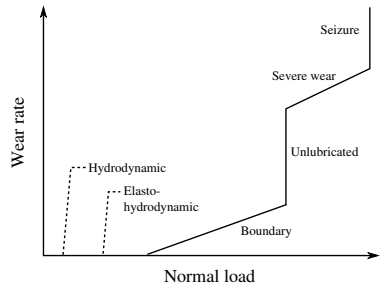
- Combination of boundary and fluid film effects
- Some asperity contact
- Film layer of one or more molecular layers
- Smooth transition
- $0.01 \mu\text{m} \leq h_{\min} \leq 1 \mu\text{m}$

# Lubrication: friction coefficient and wear



Bar diagram of friction coefficient for various lubrication conditions

B.J. Hamrock, "Fundamental of fluid film lubrication" (1991)



Wear rate for various lubrication regimes

Beerbower (1972)

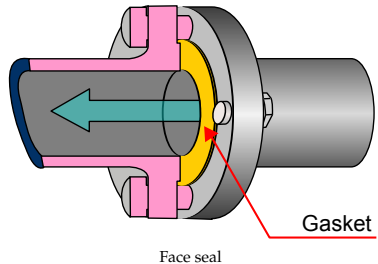
# Lubrication: take home messages

- Lubrication: reduction of wear and friction between relatively moving surfaces by adding lubricant
- Hydrodynamic: full separation of solids, thin fluid film lubrication (Reynolds equation), dynamic viscosity is important
- EHL: solids deform elastically (hard - metals, soft - polymers), affected by viscosity-pressure dependence
- Boundary: contact of asperities, but still thin molecular level of lubricant, chemical properties important, breakdown of fluid film
- Mixed (partial): smooth transition
- Recommended literature:
  - 1 B.J. Hamrock et al, "Fundamentals of fluid film lubrication" (2004)
  - 2 F.P. Bowden and D. Tabor, "The friction and Lubrication of Solids (1950)
  - 3 D. Dowson, "Elastohydrodynamic and micro-elastohydrodynamic lubrication", *Wear*, 190 (1995)



# Sealing: what is it?

- **Sealing:** technique to prevent or reduce leakage of fluid from one chamber to another using seals
- Different types:
  - face seals
  - O-ring seals
  - labyrinth seals
- Dynamic/static
- Material: polymer/metallic
- Operate in EHL/mixed/boundary regimes



O-ring

# Application: metal-to-metal static face seal

- Metal-to-metal static face seals used in fluid system of nuclear power plants
- Coating of the seal is made of material Norem<sup>[1]</sup>: elasto-plastic  
Elastic moduli:

$$E = 175 \text{ GPa}, \nu = 0.3$$

Yield stress:

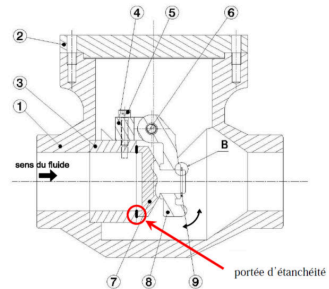
$$\sigma_Y = R_0 + Q(1 - e^{-bp})$$

$$R_0 = 442.7 \text{ MPa}$$

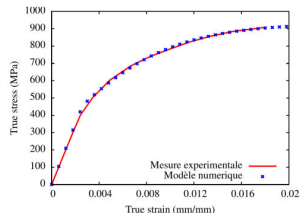
$$Q = 493.5 \text{ MPa}$$

$$b = 242.2$$

J. Durand, PhD thesis (2012)

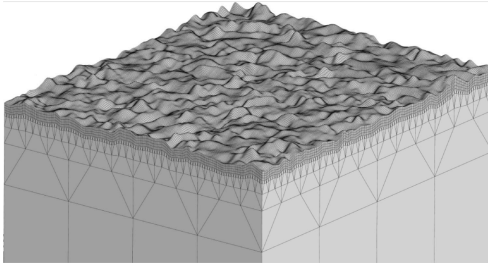


Sketch of a valve<sup>[1]</sup>

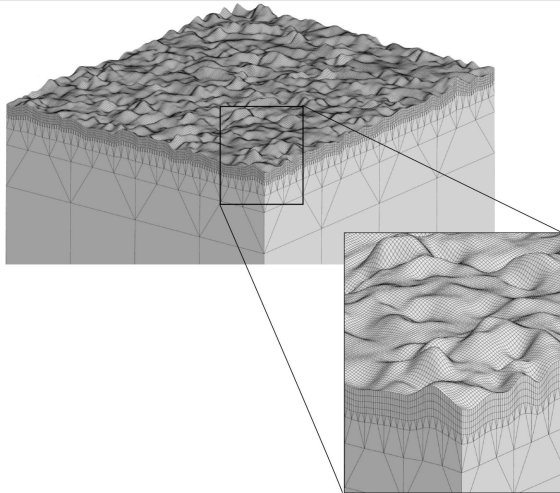


Material behavior of Norem<sup>[1]</sup>

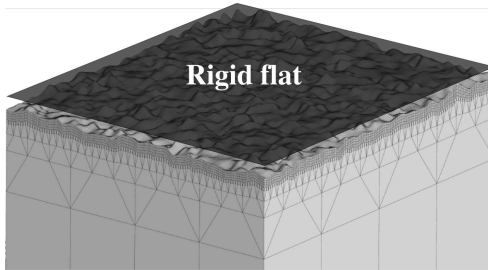
# Problem statement



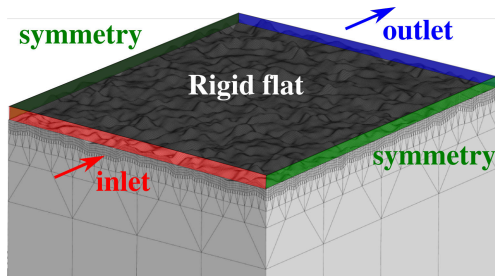
# Problem statement



# Problem statement



# Problem statement



Surface discretization	Total DOFs	RAM	Cores	Time
$256 \times 256$	1.4M	30 Gb	8	2-4 days
$512 \times 512$	5.7M	140 Gb	16	4-8 days

# Problem statement

- Mechanical contact (unilateral):

$$\left\{ \begin{array}{ll} \nabla \cdot \underline{\underline{\sigma}}(\underline{u}) = 0 & \text{in } \Omega_s, \\ g(\underline{u}) \geq 0, \sigma_n(\underline{u}) \leq 0, g(\underline{u}) \sigma_n(\underline{u}) = 0 & \text{at } \Gamma_c, \\ \underline{u}_x|_{x=0, \lambda/2} = 0, \quad \underline{u}_y|_{y=0, L} = 0, & \end{array} \right.$$

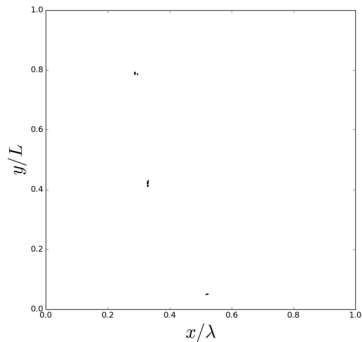
- Thin fluid flow with immobile walls (Reynolds equation):

$$\left\{ \begin{array}{ll} \nabla \cdot [g(\underline{u})^3 \nabla p_f] = 0 & \text{in } \Gamma_f \\ p_f|_{y=0} = p_i, \quad p_f|_{y=L} = p_o \\ [\nabla p_f \cdot \underline{e}_x]|_{x=0, \lambda/2} = 0, & \end{array} \right.$$

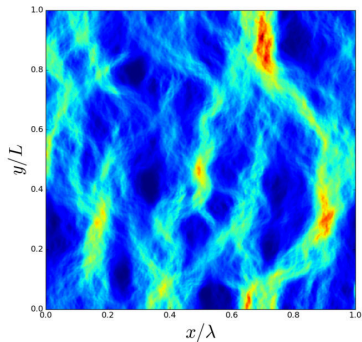
- Fluid/structure interface:

$$\sigma_n(\underline{u}) = -p_f \quad \text{at } \Gamma_f$$

# Results of the numerical simulation



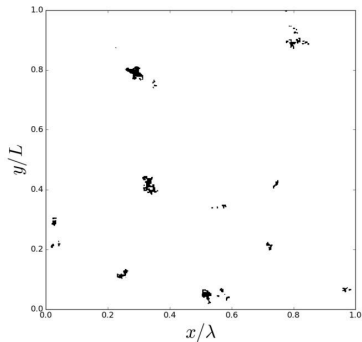
Morphology of the contact interface



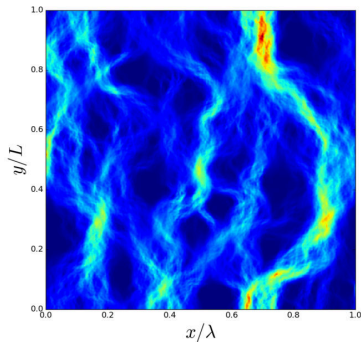
Intensity of the fluid flux



# Results of the numerical simulation

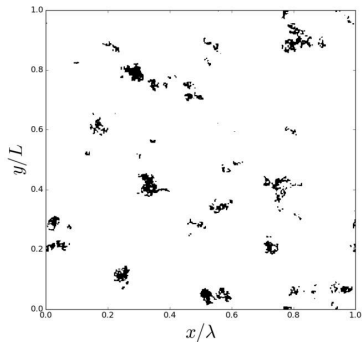


Morphology of the contact interface

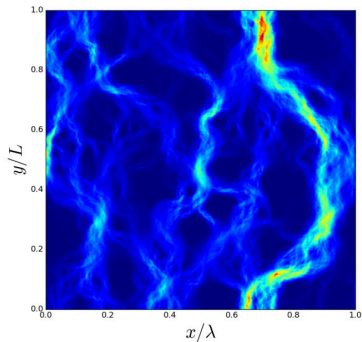


Intensity of the fluid flux

# Results of the numerical simulation

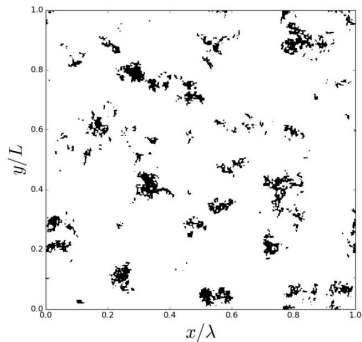


Morphology of the contact interface

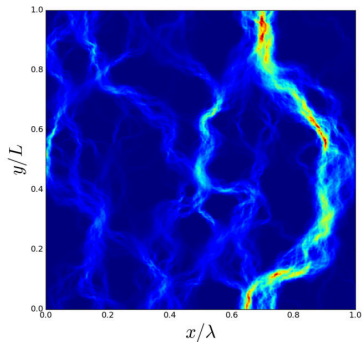


Intensity of the fluid flux

# Results of the numerical simulation

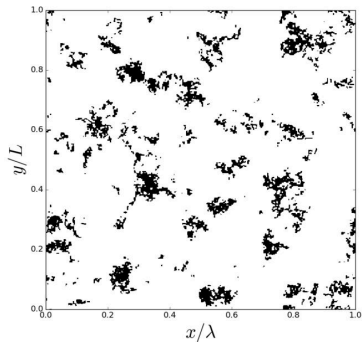


Morphology of the contact interface

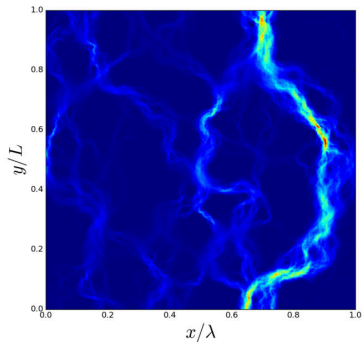


Intensity of the fluid flux

# Results of the numerical simulation

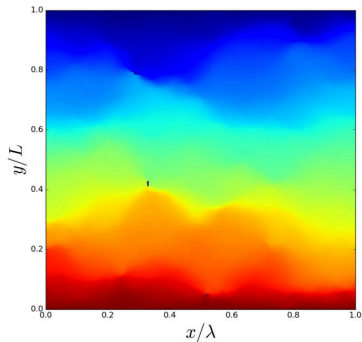


Morphology of the contact interface

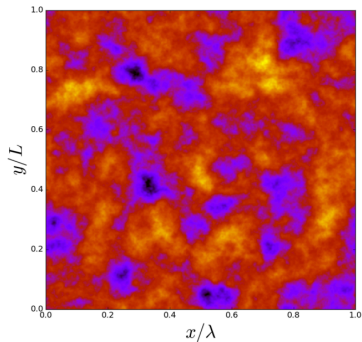


Intensity of the fluid flux

# Results of the numerical simulation

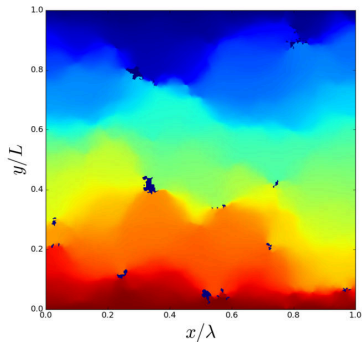


Distribution of the fluid pressure

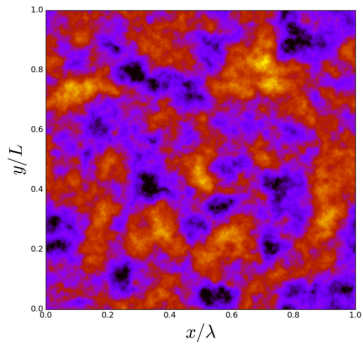


Distribution of the free volume

# Results of the numerical simulation

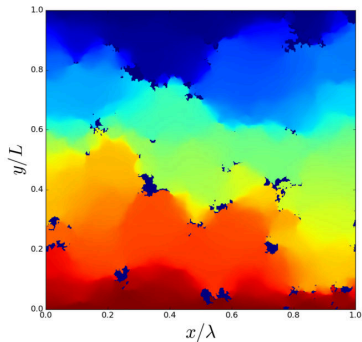


Distribution of the fluid pressure

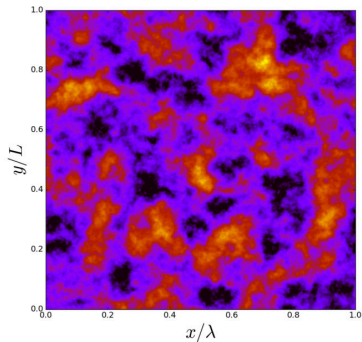


Distribution of the free volume

# Results of the numerical simulation

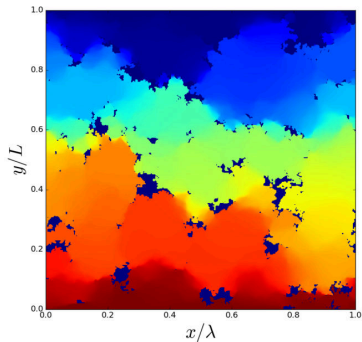


Distribution of the fluid pressure

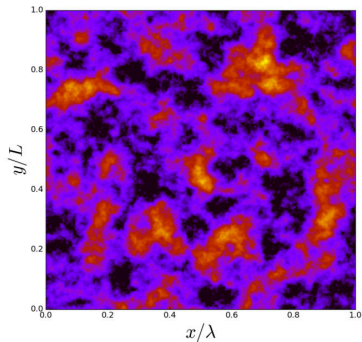


Distribution of the free volume

# Results of the numerical simulation



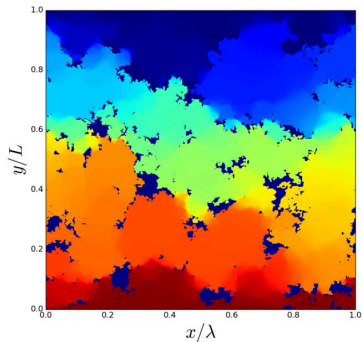
Distribution of the fluid pressure



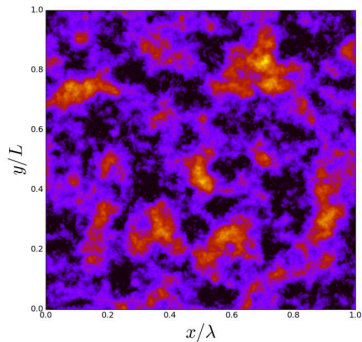
Distribution of the free volume



# Results of the numerical simulation

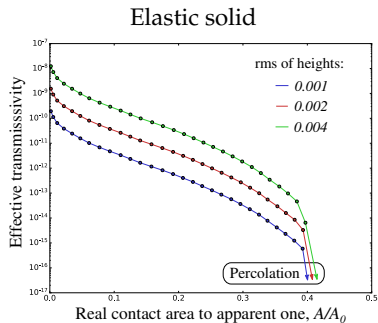


Distribution of the fluid pressure



Distribution of the free volume

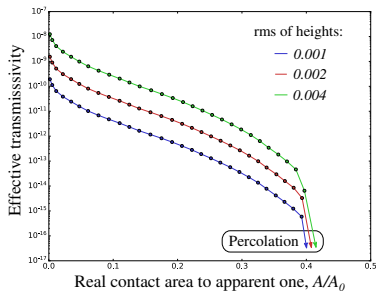
# Transmissivity of the interface



Effective transmissivity of the interface  
in case of elastic material  
(loading until percolation)

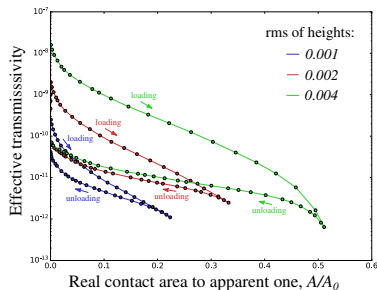
# Transmissivity of the interface

## Elastic solid

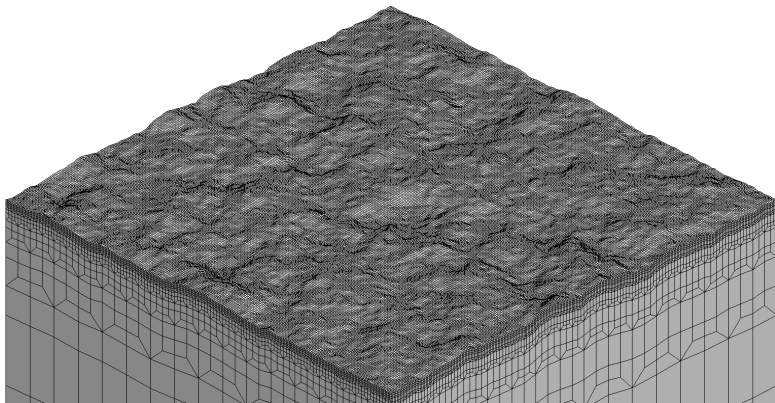


Effective transmissivity of the interface  
in case of elastic material  
(loading until percolation)

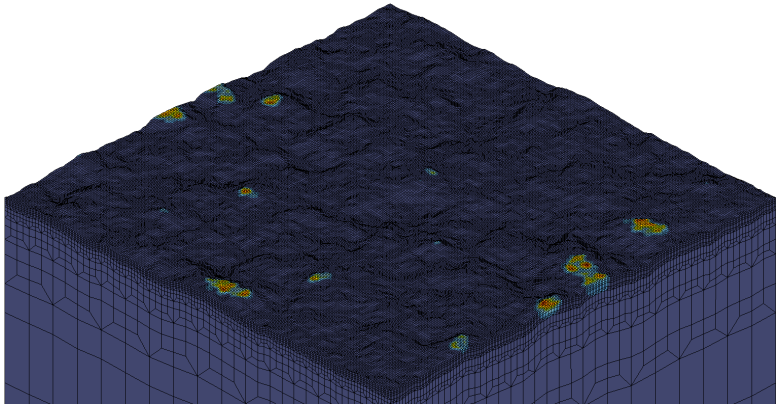
## Elasto-plastic solid



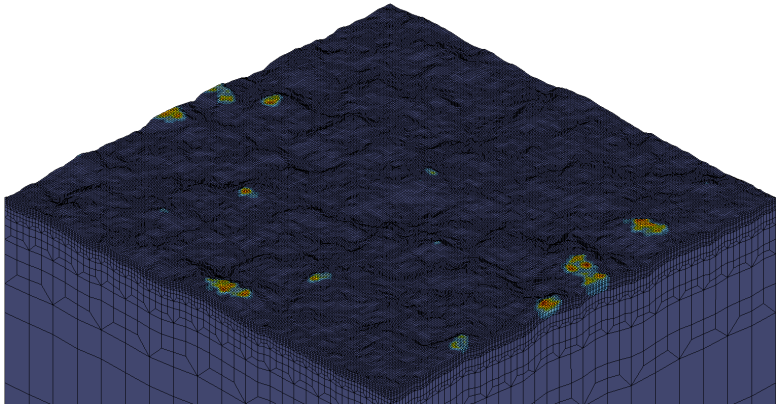
Effective transmissivity of the interface  
in case of elasto-plastic material  
(loading-unloading cycle)



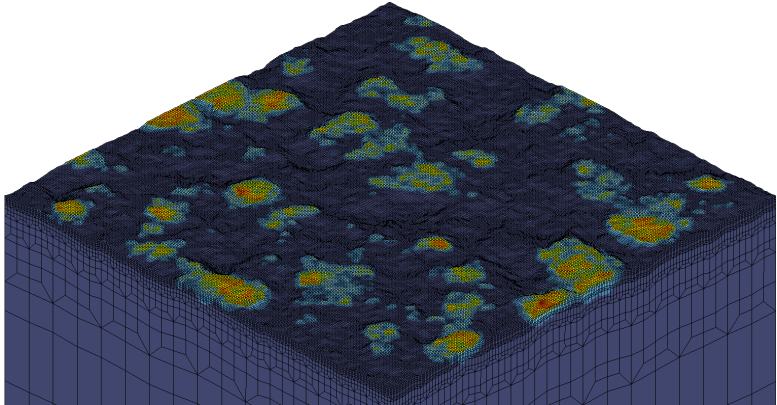
FE mesh



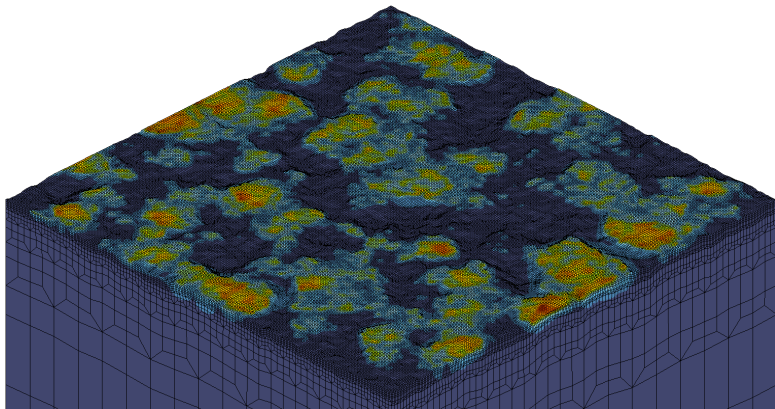
Accumulated plastic strain during *loading*



Accumulated plastic strain during *loading*

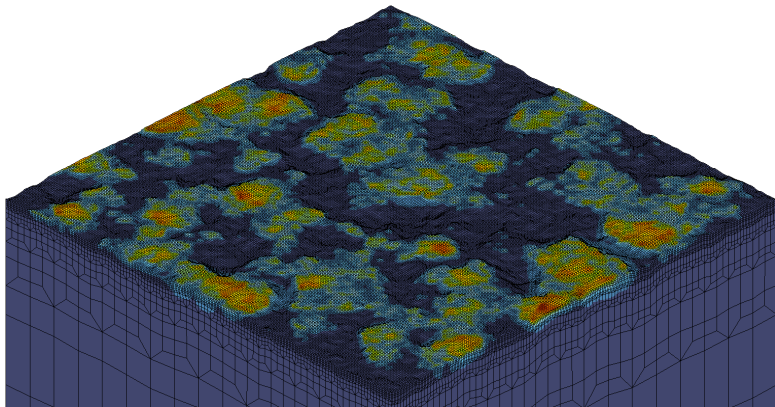


Accumulated plastic strain during *loading*



Accumulated plastic strain during *loading*





Accumulated plastic strain during *unloading*



Thank you for your attention!

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